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Structural Properties of the Disordered Spherical and Other Mean Field Spin Models

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We extend the approach of Aizenman, Sims and Starr for the SK-type models to their spherical versions. Such an extension has already been performed for diluted spin glasses. The factorization property of the optimal structures found by Guerra for the SK model, which holds for diluted models as well, is verified also in the case of spherical systems, with the due modifications. Hence we show that there are some common structural features in various mean field spin models. These similarities seem to be quite paradigmatic, and we summarize the various techniques typically used to prove the structural analogies and to tackle the computation of the free energy per spin in the thermodynamic limit.

KEY WORDS: spin glasses, diluted spin glasses, optimization problems, spherical models, overlap structures

1. INTRODUCTION

Aizenman, Sims and Starr introduced in Ref. 1 an approach to models of the type of Sherrington-Kirkpatrick (SK) of mean field spin glasses which is based on very physical ideas. Their method consists of introducing an auxiliary system to be coupled to the original one, and use it to generate trial order parameters and to find a general form for the trial free energy that bounds the actual one. They also find that the existence of thermodynamic limit of the free energy suggests the expression of an optimal trial free energy, which is difficult to compute but ensures an Extended Variational Principle: the exact free energy is obtained as an infimum in a suitable space. This approach explains in a sense the structure of the model: its main parameters, the form of the trial free energy, the trial order parameters, the probability space in which one has to search for the optimal trial free energy.

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In other words, the method tells us what is the correct physical approach to the model, i.e. coupling it to a general auxiliary system with the proper features. Guerra found in Ref. 9 a way to restrict the space in which one has to work by proving some invariance properties of the optimal structures. The whole approach seemed to rely heavily on the Gaussian nature of the couplings. On the contrary, being a very physical approach, it turned out to be quite paradigmatic, once the proper techniques for various other models were found.^(3,5) As a matter of fact, not only the same approach works when the model is diluted and loses the Gaussian nature of the couplings, but we prove here that making the model spherical either does not affect its structure. The most important starting point has to be a simpler one, though. If the method is paradigmatic it must work first of all in the simple case of the non-disordered version of the SK model: the mean field ferromagnet, that should be analogous to disordered systems from the structural point of view. This is quite the case,⁽¹⁰⁾ of course, as we will see.

The main idea is always to replace the quadratic dependance of the Hamiltonians on the main physical quantity (magnetization, overlap, etc.) by a linear approximation with suitable coefficients, generated by the auxiliary structure. Hence one compares quadratically the main physical quantity of the original system with the trial one coming from the auxiliary system, and this leads to a free energy given by the difference of an entropy term and an internal energy term. This offers important results for a large class of models, but one needs to find the proper technique to prove analogous theorems for different models.

We will start with the description of the approach in the case of the Curie– Weiss (CW) mean field ferromagnet, which provides a stereotypical example. We then show how the same method applies to the SK model and its spherical version. Lastly, we explain how and why the same results extend to diluted models, including Optimization problems.

2. MEAN FIELD MODEL OF FERROMAGNETS

The Curie–Weiss Hamiltonian is

$$H_N^{CW}(\sigma) = -\frac{J}{N} \sum_{i < j}^{1,N} \sigma_i \sigma_j ,$$

defined on Ising spin configurations $\sigma : i \to \sigma_i = \pm 1, i = 1, ..., N$. The coupling strength *J* is a positive constant. Defining the magnetization per spin of the configuration σ as

$$m(\sigma) = \frac{1}{N} \sum_{i=1}^{N} \sigma_i$$

the Hamiltonian can then be written as

$$H_N^{CW}(\sigma) = -N\frac{1}{2}Jm^2(\sigma) ,$$

so that the partition function is by definition

$$Z_N(\beta) = \sum_{\{\sigma\}} \exp\left(N\frac{1}{2}\beta Jm^2(\sigma)\right),\,$$

and the free energy is

$$-\beta f = \lim_{N} -\beta f_{N} = \lim_{N} \frac{1}{N} \ln Z_{N} ,$$

omitting the dependence on β . Notice the following fundamental formula and keep it in mind for later

$$\partial_{\beta} \frac{1}{N} \ln Z_N(\beta) = \frac{1}{2} J \langle m^2 \rangle;$$
 (1)

here $\langle \cdot \rangle$ denotes the Boltmann-Gibbs average.

2.1. Magnetization Structures and the Comparison Method

Consider some discrete space Σ , some weights $\xi_{\tau}, \tau \in \Sigma$ and a magnetization kernel $\tilde{m} : \Sigma^2 \to [-1, 1]$. The triple (Σ, ξ, \tilde{m}) is called *Magnetization Structure* (MaSt). Then for a given MaSt \mathcal{M} define the trial function

$$G_N(\mathcal{M}) = \frac{1}{N} \ln \frac{\sum_{\sigma, \tau} \xi_\tau \exp(\beta J N m \tilde{m})}{\sum_\tau \xi_\tau \exp\left(\frac{1}{2} \beta J N \tilde{m}^2\right)}$$
(2)

The idea is to compare the trial magnetization \tilde{m} with the actual magnetization of the original system. In the simple case of the CW model we do not need such a rich structure, but it serves as an introduction to the methods. For a very formal treatment of such methods for classical spin systems, an excellent reference is.⁽¹³⁾

2.1.1. Generalized MaSt Bound

Consider the following special MaSt $\mathcal{M}_{\tilde{m}}$. Let Σ be any space and ξ be any weights in this space. Take an auxiliary CW system of M spins, with onebody interactions, i.e. with Hamiltonian linear in the magnetization. Assume the coupling is still J, and the temperature is $\tilde{\beta}$. It is easy to compute the mean magnetization \tilde{m} in this system

$$\tilde{m} = \tanh \beta J$$
,

which we can modulate between zero and one by changing the temperature (or equivalently the strength of the couplings). Now take this fixed value \tilde{m} (constant over all Σ) as the trial magnetization of our MaSt $\mathcal{M}_{\tilde{m}}$, and plug it into (2). We get

$$G_N(\mathcal{M}_{\tilde{m}}) = \frac{1}{N} \ln \sum_{\sigma} \exp(\beta J N \, m \tilde{m}) - \frac{1}{N} \ln \exp\left(\frac{1}{2} \beta J N \tilde{m}^2\right)$$
(3)

since \tilde{m} does not depend on the points $\tau \in \Sigma$. Notice that $NG_N(\mathcal{M}_{\tilde{m}})$ coincides with the logarithm of the partition function $Z(H_N^{CW}(m^2))$, provided we replace the squared magnetization m^2 with the trivial quadratic estimate $m^2 \ge 2m\tilde{m} - \tilde{m}^2$ which, as $G_N(\mathcal{M}_{\tilde{m}})$ is easy to compute, brings the consequent inequality, holding for all N

$$\frac{1}{N}\ln Z_N(\beta) \ge \sup_{\tilde{m}} \left\{ \ln 2 + \ln \cosh(\beta J\tilde{m}) - \frac{1}{2}\beta J\tilde{m}^2 \right\} = \sup_{\tilde{m}} G_N(\mathcal{M}_{\tilde{m}}) .$$
(4)

Notice that $G_N(\mathcal{M}_{\tilde{m}})$ does not depend on *N*. Physically speaking, we replaced the two-body interaction, which is difficult to deal with, with a one-body interaction. Then we try to compensate this by modulating the field acting on each spin by means of a trial fixed magnetization (entropy term), and a correction term (the internal energy), quadratic in this trial magnetization \tilde{m} .

In general, we can state (see also Ref. 13 for a different perspective) the following.

Theorem 1. For any value of $N \in \mathbb{N}$, the trial function G_N defined by (2) is a lower bound for the pressure $-\beta f_N$ of the CW model

$$-\beta f_N \ge \sup_{\mathcal{M}} G_M(\mathcal{M}),\tag{5}$$

Let us emphasize that a fundamental property of the CW model is that, for any \tilde{m} (non constant on Σ in general), the inequality

$$m \ge 2m\tilde{m} - \tilde{m}^2 \tag{6}$$

implies a correspondent inequality for the free energy per spin.

Another fundamental application of the fact that convex inequalities for the magnetization imply inequalities for the free energy is the proof of the existence of the thermodynamic limit of the free energy per spin.^(11,13) The proof relies on considering two CW systems, one with N spins and another one with M spins, then comparing these two independent systems with the system consisting of the union of the two, which is a CW model with N + M spins.

2.1.2. Reversed Bound and Variational Principle

The just mentioned existence of the thermodynamic limit of the free energy density, guarantees that the following Cesàro limit offers the value of such a limit

$$\mathbf{C}\lim_{M} \frac{1}{N} \ln \frac{Z_{M+N}}{Z_M} = -\beta f. \tag{7}$$

Now assume $M \gg N$. Clearly Z_{M+N} splits into the sum of three terms. One contains the interactions between spins in the big system, one contains the interactions between one spin in the big system and one in the small system, one contains the interactions between spins in the small system. The latter is negligible (by convexity arguments). This means that the spins in the small system are decoupled by the addition of the large system, and they do not interact one another (in the M-limit). If we take the term with the interactions within the large system (or cavity) as the weight $\xi_{\tau,\tau} \tau$ as the spin configuration in $\Sigma = \{-1, +1\}^M$, then the left hand side of (7) is the trial function $G_N(\mathcal{M}_B(M))$ (which does not depend on N) with the special choice just described, called Boltzmann MaSt $\mathcal{M}_B(M)$. In fact, the Boltzmann factor in the denominator with Z_N can be written as ξ times a properly renormalized CW Hamiltonian, like in (3). So we get the following.

Theorem 2. (Reversed Bound) If we plug the Boltzmann MaSt $\mathcal{M}_B(M)$ just defined above into the trial function G_N defined by (2), then the Boltzmann trial function $G_N(\mathcal{M}_B(M))$ provides, in the thermodynamic limit, an upper bound for the CW pressure $-\beta f$

$$-\beta f \leq \lim_{N \to \infty} \limsup_{M \to \infty} G_N(\mathcal{M}_B(M)) = \lim_{N \to \infty} G_N(\mathcal{M}_B) ,$$

as a consequence of

$$-\beta f = \mathbf{C} \lim_{M} \frac{1}{N} \ln \frac{Z_{M+N}}{Z_M} \le \limsup_{N} \limsup_{M} \limsup_{M} G(\mathcal{M}_B(M)) \equiv G(\mathcal{M}_B) .$$
(8)

Therefore we have the reversed bound to (5), and thus the following.

Theorem 3. (Extended Variational Principle) Taking the supremum, for each N separately, of the trial function $G_N(\mathcal{M})$ over the whole MaSt space, the resulting sequence tends to the limiting pressure $-\beta f$ of the CW model as N tends to infinity

$$-\beta f = \limsup_{N} \sup_{\mathcal{M}} G_N(\mathcal{M}) .$$
(9)

In order to compute explicitly f, one can proceed as follows.⁽¹⁰⁾ Let us notice that the magnetization m can take only 2N + 1 distinct values. We can therefore

split the partition function into sums over configurations with constant magnetization in the following way

$$Z_N(\beta) = \sum_{\sigma} \sum_{\tilde{m}} \delta_{m\tilde{m}} e^{\frac{1}{2}\beta J m\tilde{m}N} \Leftarrow \sum_{\tilde{m}} \delta_{m\tilde{m}} = 1.$$
(10)

Now inside the sum $m = \tilde{m}$, or better $m^2 = \tilde{m}^2$, which means also $m^2 = 2m\tilde{m} - \tilde{m}^2$. Plugging such a quadratic *equality* into $Z_N(\beta)$ and using the trivial inequality $\delta_{m\tilde{m}} \leq 1$ yields

$$Z_N(\beta) \leq \sum_{\tilde{m}} \sum_{\sigma} e^{\beta J m \tilde{m}} e^{-\frac{1}{2}\beta J N \tilde{m}^2}.$$

But this clearly means that

$$Z_N(\beta) \le \sum_{\tilde{m}} \sup_{\tilde{m}} \left\{ \ln 2 + \ln \cosh(\beta J \tilde{m}) - \frac{1}{2} \beta J \tilde{m}^2 \right\}$$

from which

$$\frac{1}{N}\ln Z_N(\beta) \le \frac{\ln(2N+1)}{N} + \sup_{\tilde{m}} \left\{ \ln 2 + \ln \cosh(\beta J\tilde{m}) - \frac{1}{2}\beta J\tilde{m}^2 \right\}$$

This gives, together with (4), the exact value of free energy per site at least in the thermodynamic limit. The presence of the correction term $\ln(2N + 1)/N$ is typical of these kinds of bounds, and as a consequence one can usually get the exact value of the free energy only in the thermodynamic limit (but compare to Proposition 5 in Ref. 13 for the special case of classical spin systems).

2.2. Spherical Ferromagnetic Model

The calculation of the free energy of the spherical version of the CW model is more involved than the Ising case just illustrated. Still, the computation can be performed ⁽²⁾ and the it can be reproduced in the framework of the Magnetization Structures, but we will present here in detail only the disordered case.

3. DISORDERED MEAN FIELD MODELS OF SPIN GLASSES

The Hamiltonian of the Sherrington-Kirkpatrick (SK) model comes from the CW one where we take independent centered unit Gaussian couplings $\{J_{ij}\}$ as opposed to constant ones, after a proper rescaling:

$$H_N(\sigma, h; J) = -\frac{1}{\sqrt{N}} \sum_{i < j}^{1, N} J_{ij} \sigma_i \sigma_j.$$
(11)

The Hamiltonian is in some sense still quadratic in the quantity that takes the place of the magnetization: being a centered Gaussian, the Hamiltonian is determined by its covariance

$$\mathbb{E}(H(\sigma)H(\sigma')) = Nq^2(\sigma, \sigma'), q(\sigma, \sigma') = \frac{1}{N} \sum_{i=1}^N \sigma_i \sigma_i'$$

where \mathbb{E} will denotes the expectation with respect to the J.'s, and q is the overlap between two replicas. Notice (and compare with the analog in the CW model) that

$$\partial_{\beta} \frac{1}{N} \mathbb{E} \ln Z_N(\beta) = \frac{\beta}{2} (1 - \langle q^2 \rangle) , \qquad (12)$$

where $\langle \cdot \rangle$ denotes the composition of the Boltmann–Gibbs (Ω) average (taken first), followed by the *quenched* expectation (\mathbb{E}). The key tool employed to make the calculation above is the Gaussian integration by parts.

As the SK model is random (because of the random couplings) and the overlap plays a role similar to that of the magnetization for the CW model, it is expected that the analog of the MaSt for disordered model is the Random Overlap Structure (ROSt), given in the following.

Definition 1. A Random Overlap Structure \mathcal{R} is a triple (Σ, \tilde{q}, ξ) where

- \sum is a discrete space;
- $\xi : \sum \to \mathbb{R}_+$ is a system of random weights; $\tilde{q} : \Sigma^2 \to [0, 1], |\tilde{q}| \le 1$ is a positive definite Overlap Kernel (equal to 1) only on the diagonal of Σ^2).

Now consider two families of independent centered Gaussian random variables \tilde{H} . and \hat{H} , defined on $\Sigma \ni \gamma$, such that

$$\mathbb{E}(\tilde{H}_{i}(\gamma)\tilde{H}_{j}(\gamma')) = N2\tilde{q}_{\gamma\gamma'}\delta_{ij}, \quad \mathbb{E}(\hat{H}(\gamma)\hat{H}(\gamma')) = N\tilde{q}_{\gamma\gamma'}^{2}$$
(13)

and consider $\tilde{H} = \sum_{i=1}^{N} \tilde{H}_i \sigma_i$. Then we define, in analogy with (2), the *Generalized Trial Function* by

$$G_N(\mathcal{R}, \tilde{H}, \hat{H}) = \frac{1}{N} \mathbb{E} \ln \frac{\sum_{\sigma, \tau} \xi_\tau \exp(-\beta \tilde{H})}{\sum_\tau \xi_\tau \exp(-\beta \hat{H})}.$$
 (14)

At this point we can use interpolation ⁽¹¹⁾ to prove ⁽¹⁾ the following.

Theorem 4. (Generalized Bound) For any value of $N \in \mathbb{N}$, the trial function G_N defined by (14) is an upper bound for the pressure $-\beta f_N$ of the SK model

$$-\beta f_N \leq \inf_{\mathcal{R}} G_N$$
.

The proof can be found in Ref. 1. To see why this inequality has the same nature as the analogous one for the CW model, i.e. Ref. 5, we have to recall (12) and notice that, thanks to a differentiation with respect to the interpolating parameter, the theorem above is guaranteed by the analog of Ref. 6 for the covariances of the three Hamiltonians H, \hat{H} , \hat{H} we used

$$q^2 \le 2q\tilde{q} - \tilde{q}^2 \ . \tag{15}$$

The same result for the CW model could be proven by interpolation too, but that case is so simple that interpolation would have been a further unnecessary complication. In order to emphasize even more the key role of Ref. 15, like for the CW, let us understand that the theorem above is part of the following general comparison scheme (see Refs. 10 and 11 and references therein).

Theorem 5. Let U_i and \hat{U}_i , for i = 1, ..., K, be independent families of centered Gaussian random variables, whose covariances satisfy the inequalities for generic configurations

$$\mathbb{E}(U_i U_j) \equiv S_{ij} \ge \mathbb{E}(\hat{U}_i \hat{U}_j) \equiv \hat{S}_{ij}, \quad \mathbb{E}(U_i U_j) \equiv S_{ii} = \mathbb{E}(\hat{U}_i \hat{U}_i) \equiv \hat{S}_{ii},$$

then for the quenched averages we have the inequality in the opposite sense

$$\mathbb{E}\ln\sum_{i}w_{i}\exp(U_{i})\leq\mathbb{E}\ln\sum_{i}w_{i}\exp(\hat{U}_{i})$$

where the $w_i \ge 0$ are the same in the two expressions.

The proof $^{(10,11)}$ is very simple, and based on interpolation. A very important application, other than the ROSt approach—which includes as a special realization the Parisi trial function, is the proof of the existence of thermodynamic limit of the free energy density.^(11,12)

Now take $\Sigma = \{-1, 1\}^M$, and denote by τ the elements of Σ . We clearly have in mind an auxiliary spin systems. In fact, we also choose

$$\tilde{H}_{.} = -\sum_{k=1}^{M} J_{.}^{k} \tau_{k}, \quad \hat{H} = -\sqrt{\frac{N}{2}} \sum_{k,l}^{1,M} J^{k,l} \tau_{k} \tau_{l}$$

which satisfy (13). Let us also chose $\xi_{\tau} = \exp(-\beta H_M^{SK}(\tau))$. Then, if we call $\mathcal{R}_B(M)$ the Boltzmann ROSt just defined, we can prove ⁽¹⁾ the following.

Theorem 6. (Reversed Bound) If we plug the Boltzmann ROSt $\mathcal{R}_B(M)$ just defined above into the trial function G_N defined by (14), then the Boltzmann trial function $G_N(\mathcal{R}_B(M))$ provides, in the thermodynamic limit, a lower bound for the

SK pressure $-\beta f$

$$-\beta f \geq \lim_{N \to \infty} \liminf_{M \to \infty} G_N(\mathcal{R}_B(M)) = \lim_{N \to \infty} G_N(\mathcal{R}_B) .$$

Like for CW, the idea of the proof is that

$$G_N(\mathcal{R}_B(M)) \sim \frac{1}{N} \mathbb{E} \ln \frac{Z_{N+M}}{Z_M} \Leftarrow M \gg N.$$

From the two previous theorems we get immediately the completion of the analogy with CW through the following.

Theorem 7. (Extended Variational Principle) Infimizing for each N separately the trial function $G_N(\mathcal{R})$ over the whole ROSt space, the resulting sequence tends to the limiting pressure $-\beta f$ of the SK model as N tends to infinity

$$-\beta f = \lim_{N \to \infty} \inf_{\mathcal{R}} G_n \; .$$

Proving the reversed bound with the proper structure (the Parisi one), is not as easy as for ferromagnets. In fact, while the magnetization is just a number and one can fix it without too many complications like in Ref. 10, the overlap is a random variable. Therefore one has to introduce two replicas and splitting the partition function into terms with fixed overlap brings a lot of difficulties.⁽¹⁵⁾

Getting back to the general approach, Guerra⁽⁹⁾ found the following factorization property of optimal ROSt's.

Theorem 8. In the whole region where the parameters are uniquely defined, the following Cesàro limit is linear in N and $\bar{\alpha}$

$$C \lim_{M} \mathbb{E} \ln \Omega_{M} \left\{ \sum_{\sigma} \exp \left[-\beta \sum_{i=1}^{N} \tilde{H}_{i} \sigma_{i} + \lambda \hat{H} \right] \right\} = N \left(-\beta f + \frac{\beta^{2}}{2} (1 - \langle \tilde{q}^{2} \rangle) \right) + \frac{\lambda^{2}}{2} (1 - \langle \tilde{q}^{2} \rangle).$$
(16)

Notice that the analogous factorization holds a *fortiori* in the ferromagnetic case, where the spin are the only variables and there is no quenched disorder that can jeopardize the factorization.

3.1. Generalized Random Energy Model

The same construction we saw is reproducible in the simpler case of the Random Energy Model and the Generalized Random Energy Model. In this case the model is sufficiently simple to allow for a relatively simple proof of the reversed bound. For an introduction of the model and a detailed description of the relative ROSt approach we refer to Ref. 8.

4. SPHERICAL MODELS

Let

$$S_N = \left\{ \sigma \in \mathbb{R}^N : \sum_{i=1}^N \sigma_i^2 = N \right\}$$

be equipped with its normalized surface measure $d\mu_{S_N}$. With *J* we will denote again a centered unit Gaussian random variable, and any index or symbol appended to it will refer to independent identically distributed copies. For $\sigma \in S_N$ the Hamiltonian of the spherical model is the following centered Gaussian

$$H = H_N(\sigma) = -\frac{1}{\sqrt{N}} \sum_{i,j}^{1,N} j_{ij} \sigma_i \sigma_j$$

We do not consider the presence of an external field, but all the results trivially extend to this case as well. By ω we mean again the Bolztmann-Gibbs average of any observable $\mathcal{O}: S_N \to \mathbb{R}$, that now will be of the form

$$\omega(\mathcal{O}) = Z_N^{-1} \int_{SN} \mathcal{O}(\sigma) \exp(-\beta H) d\mu_{S_N}, \quad Z_N = \int_{S_N} \exp(-\beta H) d\mu_{S_N}.$$

Nothing changes in the expression of the internal energy when the model is taken spherical

$$\partial_{\beta} \frac{1}{N} \mathbb{E} \ln Z_N = \frac{\beta}{2} (1 - \langle q^2 \rangle).$$
 (17)

4.1. Generalized Bound and Extended Variational Principle

When the model is spherical, we still use the ROSt defined in the previous section, except here the space Σ in not discrete, and the two auxiliary Hamiltonians \tilde{H} and \hat{H} , defined on $\Sigma \ni \gamma$, are still Gaussian random variables such that

$$\mathbb{E}(\tilde{H}_i(\gamma)\tilde{H}_j(\gamma')) = N2\tilde{q}(\gamma,\gamma')\delta_{ij}, \quad \mathbb{E}(\hat{H}(\gamma)\hat{H}(\gamma')) = N\tilde{q}^2(\gamma,\gamma')$$

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and $\tilde{H} = \sum_{i=1}^{N} \tilde{H}_i \sigma_i$ Then plug the interpolating Gaussian Hamiltonian $H_t = \sqrt{t}(H_N + \hat{H}) + \sqrt{1 - t}\tilde{H}$ into

$$R_t = \frac{1}{N} \mathbb{E} \ln \frac{\int_{\Sigma} \int_{\sigma} \xi_{\gamma} \exp(-\beta H_t)}{\int_{\Sigma} \xi_{\gamma} \exp(-\beta \hat{H})}.$$

For most of the purposes, we can equivalently take either $\sigma \in \Sigma_N$ (which is the physically natural choice, and the one we will have in mind), or $\sigma \in \mathbb{R}^N$ equipped with the product of independent Gaussian measures on the real line, so we will simply write integrals over σ without specifying which choice we make. We clearly have

$$R_0 \equiv G_N = \frac{1}{N} \mathbb{E} \ln \frac{\int_{\Sigma} \int_{\sigma} \xi_{\gamma} \exp(-\beta \tilde{H})}{\int_{\Sigma} \xi_{\gamma} \exp(-\beta \hat{H})}, \quad R_1 = \beta f_N.$$
(18)

Now we can state the following

Theorem 9. (Generalized Bound) The trial function $G_N = R_0$ defined in (18), for any ROSt \mathcal{R} an upper bound for the pressure, and therefore, for any N

$$-\beta f_N \leq \inf_{\mathcal{R}} G_N \; .$$

Proof: Thanks to (17), we can proceed by interpolation like for the SK model. In fact,

$$rac{d}{dt}R_t = -rac{eta^2}{4}\langle (q- ilde q)^2
angle \leq 0 \; ,$$

which gives the desired result because of (18).

The next definition is not exactly the expected one, as for simplicity we choose a handier one.

Definition 2. The Boltzmann ROSt \mathcal{R}_B consists of the following construction

- the ROSt space is $\Sigma = S_M^{\varepsilon} = \{x \in \mathbb{R}^M : |\frac{1}{M} \sum_{i=1}^M x_i^2 1| < \varepsilon\} \ni \tau;$
- the overlap is defined in the usual way between the spin configurations

$$\tilde{q}(\tau,\tau') = \frac{1}{M} \sum_{k=1}^{M} \tau_i \tau_i'$$

• the random weights are of the Boltzmann type

$$\xi_{\tau} = \exp(-\beta \vartheta H_M(\tau)), \quad \vartheta = \sqrt{\frac{M}{M+N}};$$

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to be used together with the following auxiliary Hamiltonians

$$\tilde{H}_{i} = -\frac{\sqrt{2}}{\sqrt{M}} \sum_{k=1}^{M} \tilde{J}_{ik} \tau_{k}, \quad \hat{H} = -\sqrt{\frac{N}{M}} \frac{1}{\sqrt{M}} \sum_{k,l}^{1,M} \hat{J}_{kl} \tau_{k} \tau_{l}.$$

The choice $\varepsilon = 0 \Leftrightarrow \tau \in S_M = \Sigma$ would do as well, but it would lead to a technically more involved problem of equivalence of ensembles. It will be clear that as we said we could also take the spin to be independent symmetric unit Gaussian variables, and hence take $\tau \in \mathbb{R}^M$ with the Gaussian product measure.

Theorem 10. (Reversed Bound) *There exists an optimal ROSt that fulfills the reversed bound to the previous theorem, or equivalently*

$$-\beta f \geq \lim_{N\to\infty} \inf_{\mathcal{R}} G_N(\mathcal{R}) .$$

Proof: We know from Talagrand's proof of the optimality of the Parisi ROSt \mathcal{R}_{P} ⁽¹⁶⁾ that

$$-\beta f = G(\mathcal{R}_P) \ge \inf_{\mathcal{R}} G_N(\mathcal{R})$$

which is enough to prove the theorem no matter what is the choice of the space where σ and τ belong to, among the three mentioned possible choices. But we want to understand why the statements holds from a more physical and geometrical point of view, using the Boltzmann structure. In a system of M + N spins we can call τ the first M and σ the other N and write

$$H_{M+N} = -\frac{1}{\sqrt{M+N}} \left[\sum_{k,l}^{1,M} \hat{J}_{kl} \tau_k \tau_l + \sqrt{2} \sum_{k \le M, i \le N} \tilde{J}_{ki} \tau_k \sigma_i + \sum_{i,l}^{1,N} J_{ij} \sigma_i \sigma_j \right].$$
(19)

Thanks to the Gaussian nature of the Hamiltonians, we notice that when M, $N \rightarrow \infty$

$$H_{M+N} \sim \vartheta(H_M + \tilde{H}) \tag{20}$$

since the third term in (19) is negligible.⁽¹⁾ Moreover, again from the property of summation of independent Gaussian variables, we have

$$\vartheta H_M + \hat{H} \sim H_M. \tag{21}$$

Let

$$\sum_{M+N}^{\varepsilon} = \left\{ x \in \mathbb{R}^{M+N} : \left| \frac{1}{M} \sum_{i=1}^{M} x_i^2 - 1 \right| > \frac{\varepsilon}{2}, \quad \left| \frac{1}{N} \sum_{i=M+1}^{M+N} x_i^2 - 1 \right| > \frac{\varepsilon}{2} \right\}.$$

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Then

$$Z_{N+M} = \int_{\Sigma_{M+N}^{\varepsilon}} \exp(-\beta H_{M+N}) + \int_{S_{M+N} \setminus \Sigma_{M+N}^{\varepsilon}} \exp(-\beta H_{M+N})$$

$$\geq \int_{\Sigma_{M+N}^{\varepsilon}} \exp(-\beta H_{M+N}) .$$

Hence we can proceed like in Ref. 1 and obtain

$$-\beta f \ge \liminf_{N} \liminf_{M} \inf_{M} \frac{1}{N} \mathbb{E} \frac{Z_{M+N}}{Z_{M}} \ge G(\mathcal{R}_{B}) \ge \inf_{\mathcal{R}} G(\mathcal{R}).$$

The inequalities above rely on the following observations. The third term in Ref. 19 is negligible,⁽¹⁾ the second can be replaced by \tilde{H} like in Ref. 20, the first is the same as the one in ξ_{τ} , the denominator of $G(\mathcal{R}_B)$ is the same as Z_M , as guaranteed by (21).

An intuition of why the Boltzmann ROSt works and the useful region is where ε is small is given by the following property ⁽¹⁷⁾ of the high-dimensional spheres

$$\lim_{M,N\to\infty}\mu_{S_{M+N}}\left(\left\{\left|\frac{1}{M}\sum_{i=1}^{M}x_i^2-1\right|>\varepsilon\right\}\bigcup\left\{\left|\frac{1}{N}\sum_{i=M+1}^{M+N}x_i^2-1\right|>\varepsilon\right\}\right\}=0$$

We have established, in the final *N*-limit, the reversed bound in Theorem 9 and hence also the following.

Theorem 11. (Extended Variational Principle) Infimizing for each N separately the trial function $G_N(\mathcal{R})$ over the whole ROSt space, the resulting sequence tends to the limiting pressure $-\beta f$ of the spherical model as N tends to infinity

$$-\beta f = \lim_{N \to \infty} \inf_{\mathcal{R}} G_N.$$

Again, the reversed bound with the proper structure (the Parisi one), is not as easy as for ferromagnets. In fact, the complication is similar to that of the SK case.⁽¹⁶⁾

4.2. Factorization Property

At the beginning of this section we gave the formula of the generalized trial function G_N and interpolated with the true pressure $-\beta f_N$. The spin configurations σ were therefore constrained in S_N and were not independent variables. This implies that the factorization property of Ref. 9 that we saw in the previous section for the SK model, cannot hold any longer. But as we are interested in the thermodynamic limit, we can replace in \tilde{H} the spins σ by independent Gaussians (and S_N by \mathbb{R}^N), and we would still get the true pressure $-\beta f$ at t = 1 in the limit.

We would not get $-\beta f_N$ at t = 1 when N is finite. Now the cavity fields give place to independent terms and, denoting by $dg(\cdot)$ the Gaussian measure on the real line, the invariance of the optimal ROSt's of Theorem 8 is reproduced for the spherical model, and we can state the following.

Theorem 12. In the whole region where the parameters are uniquely defined, the following Cesàro limit is linear in N and λ^2

$$C \lim_{M} \mathbb{E} \ln \Omega_{M} \int_{\mathbb{R}^{N}} \prod_{i=1}^{N} dg(\sigma_{i}) \exp(-\beta \tilde{H} - \lambda \hat{H})$$

= $C \lim_{M} \mathbb{E} \ln \Omega_{M} \prod_{i=1}^{N} \exp(\beta \tilde{H}_{i}\sigma_{i}) \exp(-\lambda \hat{H})$
= $N[-\beta f + \frac{\beta^{2}}{4}(1 - \langle q^{2} \rangle)] + \frac{1}{2}\lambda^{2}(1 - \langle q^{2} \rangle).$

In the last hand side above, the free energy comes from the fact that, like in Boltzmann ROSt, the argument of the logarithm of *G* is essentially Z_{M+N}/Z_M exept for the temperature shift ϑ in Ref. 20, which gives place to the second term. The third term is analogous to the second but the shift is produced by λ . In the Boltzmann ROSt $\lambda = \beta$ and since \hat{H} is at the denominator of *G* the last two terms mutually cancel out the only the free energy is left. The proof is therefore identical to that of the analogous theorem for the SK model ⁽⁹⁾ and similar to that of Theorem 11, that is why we only sketched it here.

5. DILUTE SPIN GLASSES

Once again the spin configurations are $\sigma \in \{-1, +1\}^N$. The Hamiltonian of the Viana-Bray (VB) model of dilute mean field spin glass is

$$H_N^{VB}(\sigma,\alpha;\mathcal{J}) = -\sum_{\nu=1}^{P_{\alpha N}} J_{\nu}\sigma_{i_{\nu}}\sigma_{j_{\nu}}, \quad \alpha \in \mathbb{R}_+$$

where P_{ζ} is a Poisson random variable of mean ζ , J are independent identically distributed copies of a random variable J with symmetric distribution, i., j. are independent identically distributed random variables with uniform distribution over $1, \ldots, N$. The notation is the same as in the previous sections, except \mathbb{E} will be the expectation with respect to all the (quenched) variables, i.e. all the random variables but the spins. For dilute models the fundamental parameter that, by means of differentiation, yields the expressions analogous to (1)–(12) is the

degree of connectivity α (see Ref. 3 for detailed calculations):

$$\frac{d}{d\alpha}\frac{1}{N}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta H) = \sum_{n>0}\frac{1}{2n}\mathbb{E}\tanh^{2hn}(\beta J)\left(1-\langle q_{2n}^2\rangle\right),\qquad(22)$$

where q_{2n} is the multi-overlap defined by

$$q_{2n} = \frac{1}{N} \sum_{i=1}^{N} \sigma_i^{(1)} \dots \sigma_i^{(2n)}.$$

Notice that, despite the remarkable similarity with the analogous expression in the case of non-dilute models, (22) is not the internal energy per spin.

Here the key tool employed to make this calculation, that plays the same role as the Gaussian integration by parts for Gaussian models, is the following property of the Poisson measure $\pi_{\zeta}(m)$

$$\frac{d}{dt}\pi_{t\varsigma}(m) = \zeta(\pi_{t\varsigma}(m-1) - \pi_{t\varsigma}(m)).$$

So in the various models discussed so far, the tool changes according to the nature of the model, but the results are always pretty much alike: quadratic in the the main physical quantity, i.e. the magnetization, the overlap, the multi-overlap.

It should be clear now from (22) that the proper structure to introduce for diluted models is the one given in the next.

Definition 3. (A Random Multi-Overlap Structure) \mathcal{R} is a triple $(\sum, \{\tilde{q}_{2n}\}, \xi)$ where

- \sum is a discrete space;
- $\xi : \sum \to \mathbb{R}_+$ is a system of random weights; $\tilde{q}_{2n} : \Sigma^{2n} \to [0, 1], n \in \mathbb{N}, |\tilde{q}| \le 1$ is a positive definite Multi-Overlap Kernel (equal to 1 only on the diagonal of Σ^{2n}),

As expected, we also need to introduce the two random variables $\tilde{H}.(\gamma, \alpha; \tilde{J})$ and $\hat{H}(\gamma, \alpha; \hat{J})$ such that

$$\frac{d}{d\alpha}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta\tilde{H}.) = 2\sum_{n>0}\frac{1}{2n}\mathbb{E}\tanh^{2n}(\beta J)(1-\langle\tilde{q}_{2n}\rangle) \quad (23)$$

$$\frac{d}{d\alpha}\frac{1}{N}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta\hat{H}) = \sum_{n>0}\frac{1}{2n}\mathbb{E}\tanh^{2n}(\beta J)(1-\langle\tilde{q}_{2n}^2\rangle)$$
(24)

to be used in the usual trial function

$$G_N(\mathcal{R}) = \frac{1}{N} \mathbb{E} \ln \frac{\sum_{\sigma,\tau} \xi_\tau \exp(-\beta \sum_{i=1}^N \tilde{H}_i \sigma_i)}{\sum_\tau \xi_\tau \exp(-\beta \hat{H})}$$
(25)

where \tilde{H}_i are independent copies of \tilde{H} . The identity (22) also suggests to interpolate on the connectivity in order to prove ⁽³⁾ the following analog of Theorems 5 and 4.

Theorem 13. (*Generalized Bound*) For any value of $N \in \mathbb{N}$, the trial function G_N defined by (25) is an upper bound for the pressure $-\beta f_N$ of the VB model

$$-\beta f \leq \lim_{N\to\infty} \inf_{\mathcal{R}} G_N(\mathcal{R}).$$

Again, from (22) we learn that the generalized bound is in the end equivalent to the extension to all even multi-overlap of (15)

$$q_{2n}^2 \le 2q_{2n}\tilde{q}_{2n} - \tilde{q}_{2n}^2 \ \forall \ n \in \mathbb{N}_0.$$
⁽²⁶⁾

The Boltzmann RaMOSt $^{(3)}$ is defined in total analogy with the one in the previous section

$$\sum = \{-1, 1\}^M \ni \tau, \quad \xi_{\tau} = \exp(-\beta H_M), \quad \tilde{q}_{1\dots 2n} = \frac{1}{M} \sum_{k=1}^M \tau_k^{(1)} \tau_k^{(2n)}$$

with

$$\tilde{H} = -\sum_{\nu=1}^{P_{2\alpha N}} \tilde{J}_{\nu} \tau_{k_{\nu}} \sigma_{i_{\nu}} \equiv \sum_{j=1}^{N} H_{i} \sigma_{i}, H_{i} = \sum_{\nu=1}^{P_{2\alpha}} J_{\nu}^{i} \tau_{k_{\nu}^{i}}$$
(27)

$$\hat{H} = -\sum_{\nu=1}^{P_{\alpha N}} \hat{J}_{\nu} \tau_{k_{\nu}} \tau_{l \nu}, \qquad (28)$$

and again it yields.

Theorem 14. (Reversed Bound) If we plug the Boltzmann ROSt $\mathcal{R}_B(M)$ just defined above into the trial function G_N defined by (25), then the Boltzmann trial function $G_N(\mathcal{R}_B(M))$ provides, in the thermodynamic limit, a lower bound for the VB pressure $-\beta f$

$$-\beta f \geq \lim_{N \to \infty} \liminf_{M \to \infty} G_N(\mathcal{R}_B(M)) = \lim_{N \to \infty} G_N(\mathcal{R}_B).$$

The obvious consequence is again.

Theorem 15. (Extended Variational Principle) Infimizing for each N separately the trial function $G_N(\mathcal{R})$ over the whole ROSt space, the resulting sequence

tends to the limiting pressure $-\beta f$ of the SK model as N tends to infinity

$$-\beta f = \lim_{N \to \infty} \inf_{\mathcal{R}} G_N(\mathcal{R}).$$

The physics of dilute models is still quite obscure, and the technical difficulties prohibitive (as of now). The rigorous calculation of the free energy is still missing. Still, as we showed, the structure of dilute models is similar to the one of the others. See Refs. 4, 7, 14 for recent progress on the subject.

The analogy with SK is completed by the next ⁽³⁾ result.

Theorem 16. (Factorization of optimal RaMOSt's) In the whole region where the parameters are uniquely defined, the following Cesàro limit is linear in N and $\bar{\alpha}$

$$C\lim_{M} \mathbb{E} \ln \Omega_{M} \left\{ \sum_{\sigma} \exp[-\beta(\tilde{H}(\alpha) + \hat{H}(\bar{\alpha}/N))] \right\} = N(-\beta f + \alpha A) + \bar{\alpha}A,$$

where

$$A = \sum_{n=1}^{\infty} \frac{1}{2n} \mathbb{E} \tanh^{2n}(\beta J) (1 - \langle q_{2n}^2 \rangle), \quad \tilde{H} = \sum_{i=1}^{N} \tilde{H}_i \sigma_i.$$

5.1. Optimization Problems

We conclude by briefly describing how all we just saw extends to optimization problems as well.

The Hamiltonian of the random K-SAT is a model of dilute spin glasses, that using the usual notations reads

$$H = -\sum_{\nu=1}^{P_{aN}} \frac{1}{2} (1 + J_{\nu}^{1} \sigma_{i_{\nu}^{1}}) \cdots \frac{1}{2} (1 + J_{\nu}^{K} \sigma_{i_{\nu}^{K}}),$$

where $\{i_{\nu}^{\mu}\}\$ are independent identically distributed random variables, uniformly distributed over points $\{1, \ldots, N\}$, $\{J_{\nu}^{\mu}\}\$ are independent identically distributed copies of a symmetric random variable $J = \pm 1$,

The fundamental equation we get this time $^{(5)}$ is

$$\frac{d}{d\alpha}\frac{1}{N}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta H) = \sum_{n>0}\frac{(-1)^{n+1}}{n}\left(\frac{e^{-\beta}-1}{2^{K}}\right)^{n}\langle(1+Q_{n}(q))^{K}\rangle$$
(29)

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where

$$Q_{2n}(q) = \sum_{l=1}^{n} \sum_{r_1 < \dots < r_{2l}}^{1, 2n} q_{r_1 \cdots r_{2l}}, \quad Q_{2n+1} = 0, \quad n = 1, 2, \dots$$

which explain why we can still the RaMOSt, provided we consider $\tilde{q}_{r_1 \dots r_{2l}}$: $\Sigma_{r_1} \times \dots \times \Sigma_{rl} \rightarrow [0, 1]$ instead of the mere even multi-overlap as for the Viana-Bray model.

The natural modification of the usual quantities is ⁽⁵⁾ thus

$$\frac{d}{d\alpha}\frac{1}{N}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta\tilde{H}.) = K\sum_{n>0}\frac{(-1)^{n+1}}{n}\left(\frac{e^{-\beta}-1}{2^{K-1}}\right)^{n}\langle(1+Q_{n}(\tilde{q}))^{K-1}\rangle$$
$$\frac{d}{d\alpha}\frac{1}{N}\mathbb{E}\ln\sum_{\gamma}\xi_{\gamma}\exp(-\beta\tilde{H}) = (K-1)\sum_{n>0}\frac{(-1)^{n+1}}{n}\left(\frac{e^{-\beta}-1}{2^{K}}\right)^{n}\langle(1+Q_{n}(\tilde{q}))^{K}\rangle$$

and

$$G_N(\mathcal{R}, \tilde{H}, \hat{H}) = \frac{1}{N} \mathbb{E} \ln \frac{\sum_{\sigma, \tau} \xi_\tau \exp(-\beta \sum_{i=1}^N (\tilde{H}_i)) \frac{1}{2} (1 + J_i \sigma_i)}{\sum_\tau \xi_\tau \exp(-\beta \hat{H})}$$

where \tilde{H}_i are independent copies of \tilde{H}_i , and finally

$$\tilde{H} = \sum_{i=1}^{N} \tilde{H}_i \frac{1}{2} (1 + J_i \sigma_i).$$

The same interpolation on the connectivities allows one to prove the generalized bound, which is equivalent to the non-negativity of the function $x^{K} - Kxy^{K-1} + (K-1)y^{K}$ of x and y. The obvious construction of the Boltzmann RaMOSt ⁽⁵⁾ is $\sum = \{-1, 1\}^{M}$, using τ instead of γ , $\xi_{\tau} = \exp(-\beta H_{M}(\tau))$ and

$$\begin{split} \tilde{H}_{\tau} &= -\sum_{\nu=1}^{P_{KaN}} \frac{1}{2} \left(1 + \tilde{J}_{\nu}^{1} \tau_{j_{\nu}^{1}} \right) \cdots \frac{1}{2} \left(1 + \tilde{J}_{\nu}^{K-1} \tau_{j_{\nu}^{K-1}} \right) \frac{1}{2} \left(1 + J_{\nu}^{K} \sigma_{i_{\nu}} \right) \\ \hat{H}_{\tau} &= -\sum_{\nu=1}^{P_{(K-1)aN}} \frac{1}{2} \left(1 + \hat{J}_{\nu}^{1} \tau_{j_{\nu}^{1}} \right) \cdots \frac{1}{2} \left(1 + \hat{J}_{\nu}^{K} \tau_{j_{\nu}^{K}} \right) \end{split}$$

where the independent random variables j: are all uniformly distributed over $1, \ldots, M$ and \tilde{J} ; \hat{J} : are independent copies of J. Of course the Boltzmann RaMOSt fulfills the reversed bound and leads therefore to the extended variational principle.⁽⁵⁾ Lastly the same factorization property as usual is verified here as well.⁽⁵⁾

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6. CONCLUSION

If we start from the approach of Ref. 1 for the SK model, we saw that it keeps its validity if we remove the disorder (passing to the CW model), if we dilute the model (passing to the VB), if we make the model spherical. The presence of an external field can easily taken into account in all cases. Unfortunately, the approach does not directly extend to the dilute case if the model is spherical or ferromagnetic (some interesting results can be obtained in this latter case, and we plan on reporting on this soon.⁽⁶⁾ Moreover, it is not clear what to do when interactions involve an odd number of spins. But the main open problem is probably to understand which is the right extension to finite dimensional models.

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